



School of Earth
& Space Exploration

ARIZONA STATE UNIVERSITY

Towards Automated Monitoring of Animal Movement Using Camera Networks and Deep Learning

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Arizona Game and Fish Department

Mission: To conserve, enhance, and restore Arizona's diverse wildlife resources and habitats through aggressive protection and management programs, and to provide wildlife resources and safe watercraft and off-highway vehicle recreation for the enjoyment, appreciation, and use by present and future generations





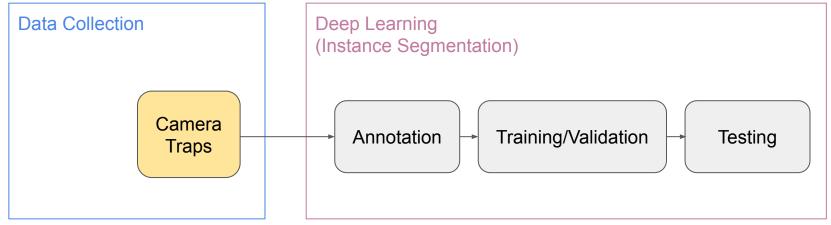
Contracts Branch

To monitor wildlife interactions with highways in order to make the most effective management decisions

Our Goals

- Make data analysis more efficient
- Minimize observer-specific bias
- Compare accuracy/precision of classification to human observers



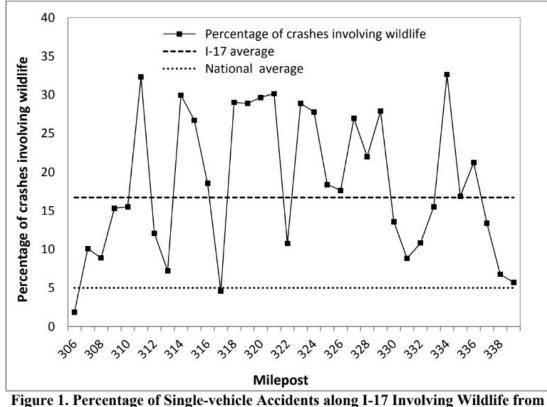


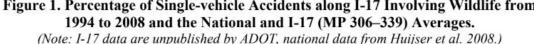
Arizona Highways





Wildlife-Vehicle Collisions

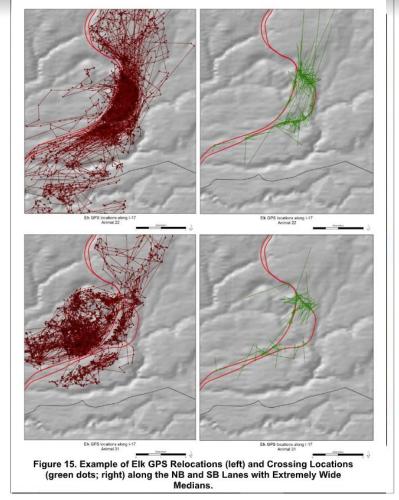




Tracking Wildlife

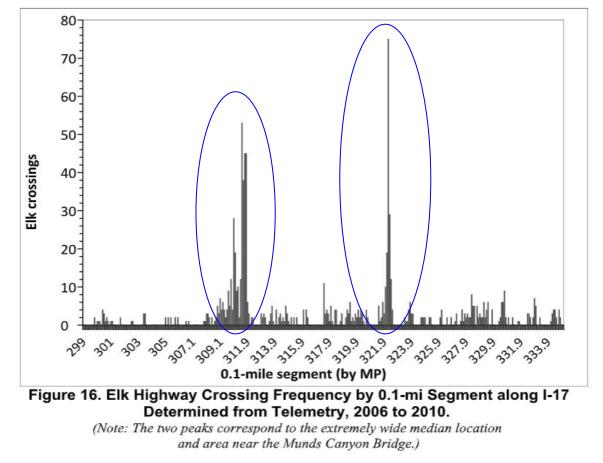






Elk Movements Associated with a High-traffic Highway: Interstate 17 Final Report 647 ADOT Research Center March 2013

Wildlife Crossing



Highway Structures

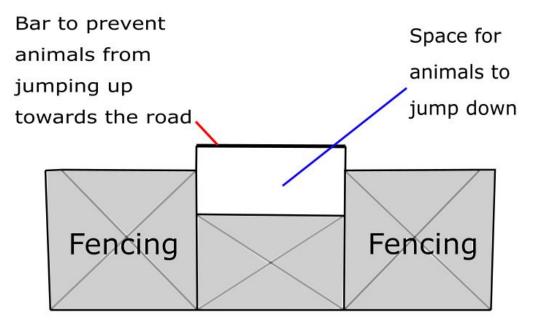


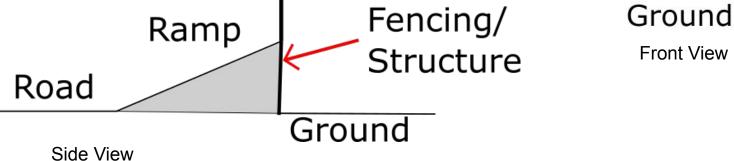
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CB MP53.6 2URS

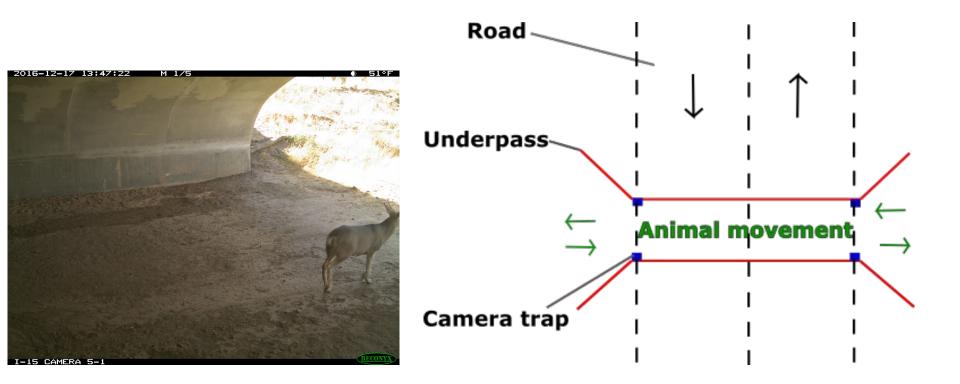
Escape Ramp







Underpass



Camera Traps

Reconyx PC800 HyperFire Professional Semi-Covert Camera Traps

- Motion triggered
- Semi-visible infrared flash
- Color images during the day, black and white images at night
- Sequence of 3-5 images at 2fps

Between 1-9 cameras monitor each structure





Problems/Challenges

- Extremely large data sets
- Wasted storage on blank photos
- Poor image quality



- Inefficient analysis methods
- User-specific bias
- False Negatives











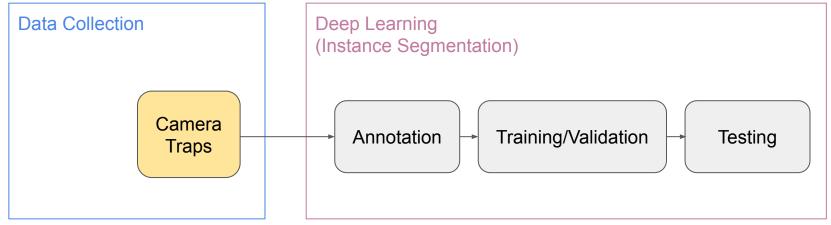




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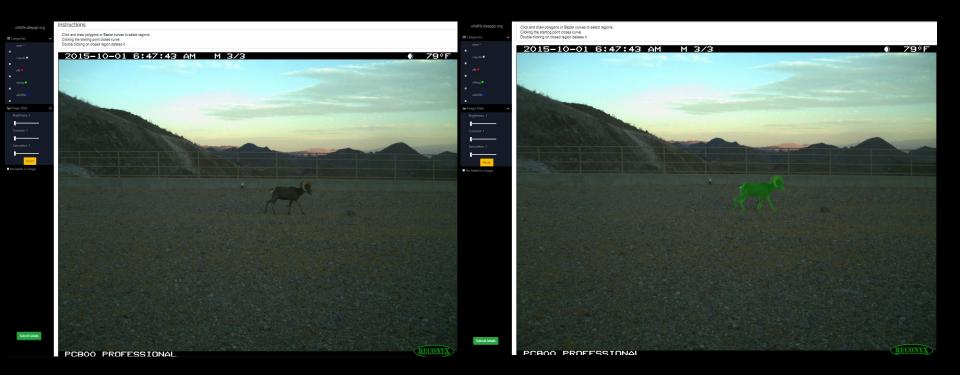


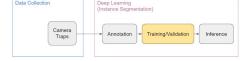




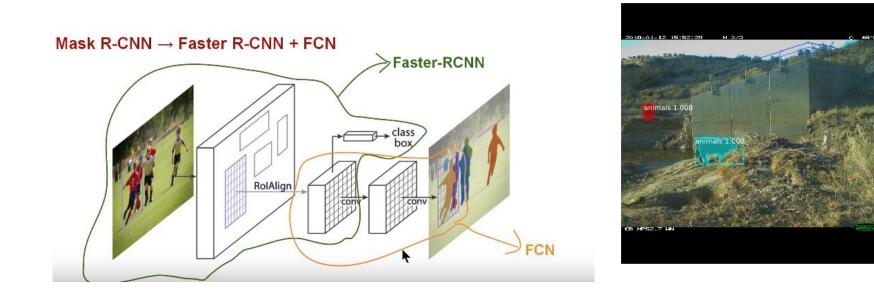
Wildlife - Annotation Tool







MaskRCNN



(He, et al. 2018)

Validation

Image #	Original Label	Prediction
0	1 deer	1 elk
1	5 sheep	3 sheep, 1 elk, 1 undetected
2	1 deer	1 deer
3	Blank	Blank
4	2 unlabeled cows	1 deer, 1 elk
5	Blank	Blank
6	1 elk	1 deer
7	2 unlabeled cows	1 deer, 1 undetected
8	1 deer	1 deer
9	1 sheep	1 elk
10	Blank	Blank
11	1 elk	1 elk
12	1 sheep	1 deer
13	Blank	Blank
14	Blank	Blank
15	1 elk	1 deer

- 88% detection accuracy
- 40% classification accuracy

Validation



Testing - Escape Ramp



ata Collection

Camera

Trans

Deep Learning

(Instance Segmentation)

Annotation

Training/Validation

Inference

- 90% detection (18/20)
- 50% classification accuracy (9/18)
- One false positive

Inference - Overpass



- 95% detection (21/22)
- 42% classification accuracy (9/21)
- No false positives

Errors



Interesting Results



Error Due to Training



- 6/9 misclassifications were due to unseen labels (cows or humans)

Future Directions

-improve detection/classification

-increase the number of species

-classify sex/relative age





- -track/count individual animals in a sequence of images
- -identify direction of travel (did it cross or not cross, coming off the highway or entering the highway)

-use it on video

-use it to verify animal actually present before wasting storage







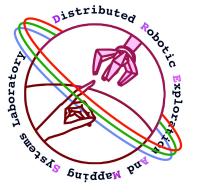




References

[1] R. Inc., RECOYNYX Hyperfire High Performance Cameras Instruction Manual, RECONYX Inc.

- [2] J. W. Gagnon, C. D. Loberger, S. C. Sprague, K. S. Ogren, S. L. Boe, and R. E. Schweinsburg, "Cost-effective approach to reducing collisions with elk by fencing between existing highway structures," Human-Wildlife Interactions, vol. 9, no. 14, 2015.
- [3] J. Gagnon, N. Dodd, K. Ogren, and R. Schweinsburg, "Factors associated with use of wildlife underpasses and importance of longterm monitoring," Journal of Wildlife Management, vol. 75, no. 6, pp. 1477–1487, 2011.
- [4] K. He, G. Gkioxari, P. Dollar, and R. Girshick, "Mask r-cnn," IEEE Transactions on Pattern Analysis and Machine Intelligence, vol. PP, no. 99, pp. 1–1, 2018.
- [5] S. W. Chen, S. S. Shivakumar, S. Dcunha, J. Das, E. Okon, C. Qu, C. J. Taylor, and V. Kumar, "Counting apples and oranges with deep learning: A data-driven approach," IEEE Robotics and Automation Letters, vol. 2, no. 2, pp. 781–788, April 2017.







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Thank you!

